

Robust B-splines estimators in generalized partly linear regression under monotone constraints

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Based on joint work with

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Semiparametric generalized partially linear model

- $y_i | (\mathbf{x}_i, z_i) \sim F(\cdot, \mu_i)$ canonical exponential family, $z_i \in [0, 1]$

$$\exp \{ [y\theta(\mathbf{x}, z) - B(\theta(\mathbf{x}, z))] / A(\kappa_0) + C(y, \kappa_0) \},$$

- $\text{VAR}(y_i | (\mathbf{x}_i, z_i)) = A^2(\kappa_0) V(\mu_i)$ with $V : \mathbb{R} \rightarrow \mathbb{R}$ known function.
- $\mu_i = \mathbb{E}(y_i | (\mathbf{x}_i, z_i)) = \mu(\mathbf{x}_i, z_i)$

$$\mu(\mathbf{x}, z) = H(\mathbf{x}^T \boldsymbol{\beta}_0 + \eta_0(z))$$

- ▶ $\boldsymbol{\beta}_0 \in \mathbb{R}^p$ is an unknown parameter.
- ▶ $\eta_0 : [0, 1] \rightarrow \mathbb{R}$ is a continuous function.
- ▶ κ_0 : nuisance parameter

Semiparametric generalized partially linear model

GPLM

$$\mu(\mathbf{x}, z) = H(\mathbf{x}^T \boldsymbol{\beta}_0 + \eta_0(z))$$



- Partial linear logistic Model
- Partial linear Poisson Model

Semiparametric generalized partially linear model

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Partial linear Model

- Partial linear logistic Model
- Partial linear Poisson Model



Symmetric errors

Semiparametric generalized partially linear model

GPLM

$$\mu(\mathbf{x}, z) = H(\mathbf{x}^T \boldsymbol{\beta}_0 + \eta_0(z))$$



Partial linear Model

- Partial linear logistic Model
- Partial linear Poisson Model



Symmetric errors

Skewed errors

Log-Gamma Model

Isotonic generalized partially linear model

- We add a **monotone constraint** on the nonparametric component:

We assume that η_0 **is non-decreasing**.

Adding monotonicity to the GPLM

In many applications, monotonicity is a desired property.

- When $\beta = \mathbf{0}$, Ramsay (1988) studied the relation between the incidence of Down's syndrome and the mother's age.
- Leitenstorfer and Tutz (2006) studied the air pollution (São Paulo) to evaluate the association between the number of daily deaths of elderly people for respiratory causes and the concentration of SO_2 , CO , PM_{10} and O_3 .
- Lu (2014) studied air pollution (Mexico City). The response y was daily death count, the covariates are
 - ▶ $z = \text{PM}_{10}$ = the daily mean ambient concentration of fine particle air pollutants $< 10\mu\text{m}$
 - ▶ \mathbf{x} = the daily mean temperature and daily rainfall indicator.

Semi-parametric estimation

When $H(t) = t$

- Huang (2002): LS under constrains.
- Lu (2010): ML estimators based on B -splines.
- Wang and Huang (2002): Robust isotonic estimators ($\beta = \mathbf{0}$).
- Álvarez and Yohai (2012): M -isotonic regression estimators ($\beta = \mathbf{0}$).
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Under a GPLM

- Boente *et al.* (2006): Robust profile kernel based estimators of η and β (*no restrictions on η*)
- Boente and Rodriguez (2010): Robust two-step kernel based estimators of η and β (*no restrictions on η*)
- Lu (2014): Monotone B -splines estimators based on the quasi-likelihood.

Spline approaches

B -spline approximation



Spline approaches

B -spline approximation



- **Monotone Splines**

Spline approaches

B -spline approximation



- **Monotone Splines**



- Monotone modification of unconstrained estimators

Dette, Neumeyer & Pilz(2006) and Neumeyer (2007)

Splines and monotonicity

Consider the knots $\mathcal{Z}_n = \{\xi_i\}_{i=1}^{m_n+2\ell}$ where

$$0 = \xi_1 = \dots = \xi_\ell < \xi_{\ell+1} < \dots < \xi_{m_n+\ell+1} = \dots = \xi_{m_n+2\ell} = 1$$

and denote as $\mathcal{S}_n(\mathcal{Z}_n, \ell)$ the class of splines of order $\ell > 1$ with knots \mathcal{Z}_n .

Schumaker (1981)

- There exist a class of B -spline basis functions $\{B_j : 1 \leq j \leq k_n\}$, with $k_n = m_n + \ell$, such that $g = \sum_{j=1}^{k_n} a_j B_j$, for any $g \in \mathcal{S}_n(\mathcal{Z}_n, \ell)$.
- The spline g is nondecreasing on $[0, 1]$ if $a_1 \leq \dots \leq a_{k_n}$.

Robust Estimators

To obtain Robust estimators, combine monotone B -splines



Loss function that
bounds residuals

$\phi : \mathbb{R}^3 \rightarrow \mathbb{R}$: loss function



Weight function
to control
the effect of leverage points

$w : \mathbb{R}^p \rightarrow \mathbb{R}$: weight
function to control leverage
of \mathbf{x}

Robust estimators

- $\hat{\kappa}$: robust consistent estimator of the nuisance parameter κ_0 .

The estimators

$$(\hat{\beta}, \hat{\eta}) = \left(\hat{\beta}, \sum_{j=1}^{k_n} \hat{a}_j B_j \right)$$

where

$$(\hat{\beta}, \hat{\mathbf{a}}) = \underset{\mathbf{b} \in \mathbb{R}^p, \mathbf{a} \in \mathcal{L}_{k_n}}{\operatorname{argmin}} \frac{1}{n} \sum_{i=1}^n \phi \left(y_i, \mathbf{x}_i^T \mathbf{b} + \sum_{j=1}^{k_n} a_j B_j(z_i), \hat{\kappa} \right) w(\mathbf{x}_i),$$

$$\mathcal{L}_{k_n} = \{ \mathbf{a} \in \mathbb{R}^{k_n} : a_1 \leq \dots \leq a_{k_n} \}.$$

Loss functions: Bounding the deviances

$$\phi(y, u, \kappa) = \rho_c[d(y; u)] + G(H(u)), \quad c = c(\kappa)$$

- ρ_c odd and bounded nondecreasing function with continuous derivative φ_c .
- c is a tuning parameter.
- G guarantees Fisher-consistency.

$$G'(s) = \int \psi_c[d(y; u)] f'(y, s) d\mu(y) = \mathbb{E}_s \left(\psi_c[d(y; u)] \frac{f'(y, s)}{f(y, s)} \right),$$

- \mathbb{E}_s expectation taken under $F(\cdot, s)$ and $f'(y, s) = \frac{\partial}{\partial s} f(y, s)$.

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When $y_i | (\mathbf{x}_i, z_i)$ has a density, $G(s) \equiv 0$ (Bianco *et al.*, 2005).

PLM: Symmetric errors

- ① Compute an unrestricted *MM*-estimator $(\hat{\beta}, \hat{\eta}) = (\hat{\beta}, \sum_{j=1}^{k_n} \hat{a}_j B_j)$

$$(\hat{\beta}, \hat{\mathbf{a}}) = \underset{\mathbf{b} \in \mathbb{R}^p, \mathbf{a} \in \mathbb{R}^{k_n}}{\operatorname{argmin}} \frac{1}{n} \sum_{i=1}^n \rho_c \left(\frac{y_i - \mathbf{x}_i^T \mathbf{b} - \sum_{j=1}^{k_n} a_j B_j(z_i)}{\hat{\sigma}} \right),$$

$\hat{\sigma}$ is the scale related to an *S*-estimator (Yohai, 1987)

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- 2 If $\hat{a}_1^{(0)} \leq \hat{a}_2^{(0)} \leq \dots \leq \hat{a}_{k_n}^{(0)}$, then

$$\blacktriangleright \hat{\beta} = \hat{\beta}^{(0)}$$

$$\blacktriangleright \hat{\eta}(z) = \sum_{j=1}^{k_n} \hat{a}_j^{(0)} B_j(z).$$

PLM: Errors with exponential unimodal density

$$y = \beta_0^T \mathbf{x} + \eta_0(z) + u,$$

- Errors density

$$g_0(u, \alpha_0) = Q(\alpha_0) \exp^{\alpha_0 \nu(u)},$$

- ▶ $\alpha_0 > 0$ an unknown parameter
- ▶ ν is a continuous function with unique maximum at u_0
- ▶ Log-Gamma case: $\nu(s) = s - \exp(s)$, $u_0 = 0$

PLM: Errors with exponential unimodal density

$$y = \beta_0^T \mathbf{x} + \eta_0(z) + u,$$

Loss function: Bianco, García Ben & Yohai (2005)

$$\phi(\mathbf{y}, \mathbf{s}, \kappa) = \rho \left(\frac{\sqrt{\mathbf{d}(\mathbf{y} - \mathbf{s})}}{\kappa} \right),$$

- $d(s) = \nu(u_0) - \nu(s)$.
- ρ a ρ -function.
- κ : tuning constant related to the parameter α_0 .

PLM: Errors with exponential unimodal density

- *MM*–estimator without restrictions

$$\left(\hat{\boldsymbol{\beta}}^{(0)}, \hat{\mathbf{a}}^{(0)} \right) = \underset{(\mathbf{b}, \mathbf{a}) \in \mathbb{R}^{\rho+k_n}}{\operatorname{argmin}} \sum_{i=1}^n \rho \left(\frac{\sqrt{d} (y_i - [\mathbf{x}_i^T \mathbf{b} + \mathbf{a}^T \mathbf{B}_i])}{\hat{\kappa}_n} \right) w(\mathbf{x}_i),$$

$\hat{\kappa}_n$ is the tuning constant as in Bianco *et al.* (2005).

PLM: Errors with exponential unimodal density

- *MM*–estimator without restrictions

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PLM: Errors with exponential unimodal density

- Otherwise, use a non-linear minimization algorithm with restrictions choosing as initial value $(\widehat{\beta}^{(0)}, \mathbf{a}^{(0)})$, where $\mathbf{a}^{(0)} \in \mathcal{L}_{k_n}$.
One possible choice for \mathbf{a}^0 is $a_1^0 = a_2^0 = 0$ and $a_i^0 = i - 2$ for $i = 3, \dots, k_n$.

▶ Details

The increasing modification: Dette, Neumeyer & Pilz (2005), Neumeyer (2007)

- $f : [a, b] \rightarrow \mathbb{R}$ define

$$\Upsilon(f)(u) = \int_a^b \mathbb{I}_{\{f(z) \leq u\}} dz + a \quad u \in \mathbb{R}$$

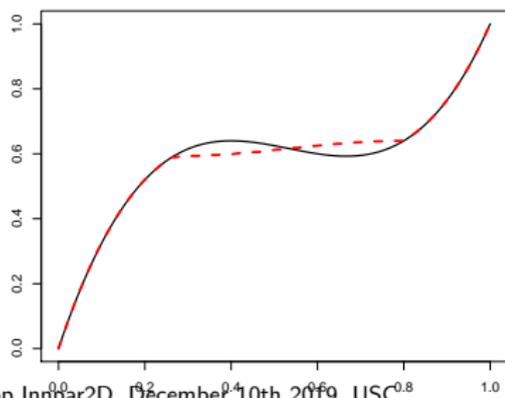
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- Given $f : [0, 1] \rightarrow \mathbb{R}$, the **Increasing modification** $f_{\text{IMOD}} : [0, 1] \rightarrow \mathbb{R}$ is

$$f_{\text{IMOD}} = \Upsilon \left(\Upsilon(f) \mathbb{I}_{[f(0), f(1)]} \right) \mathbb{I}_{[0, 1]}$$



f_{IMOD}

$f(x) =$

$$5x^3 + 4x - 8x^2 \mathbb{I}_{0 \leq x \leq 1}$$

The monotone estimator of η

A monotone estimator of $\eta : [0, 1] \rightarrow \mathbb{R}$ may be constructed as

$$\hat{\eta}_{\text{IMOD}} = \Upsilon \left(\Upsilon(\hat{\eta}) \mathbb{I}_{[\hat{\eta}(0), \hat{\eta}(1)]} \right) \mathbb{I}_{[0,1]}$$

from the unconstrained estimators.

Selection of k_n

As in He and Shi (1996) and He, Zhu & Fung (2002), define

$$BIC(k) = \log \left\{ \frac{1}{n} \sum_{i=1}^n \rho \left(y_i, \mathbf{x}_i^T \mathbf{b} + \sum_{j=1}^k \lambda_j B_j(z_i), \hat{\kappa} \right) w(\mathbf{x}_i) \right\} + \frac{\log n}{2n} k.$$

A possible criterion is to search for the first (i.e. smallest k) local minimum of $BIC(k)$ in the range of

$$\max \left(\frac{n^{1/5}}{2}, 4 \right) \leq k \leq 8 + 2n^{1/5}$$

when cubic splines are considered.

Assumptions

- $(y_i, \mathbf{x}_i, z_i)^T$ are i.i.d. observations satisfying a GPLM model with η_0 non-decreasing
- $\eta_0 \in C^r[0, 1]$ and $\eta_0^{(r)}$ is Lipschitz continuous
- The maximum spacing of the knots is of order $O(n^{-\nu})$, $0 \leq \nu \leq 1/2$
- $k_n = O(n^\nu)$ for $1/(2r + 2) < \nu < 1/(2r)$
- $\hat{\kappa} \xrightarrow{a.s.} \kappa_0$

Asymptotic results

Let $\|\eta_0 - \hat{\eta}\|_{L^2(Q)}^2 = \mathbb{E}(\eta_0(t_1) - \hat{\eta}(t_1))^2$.

- a) $\|\hat{\beta} - \beta_0\|^2 + \|\hat{\eta} - \eta_0\|_{L^2(Q)}^2 \xrightarrow{a.s.} 0$.
- b) $\gamma_n \left(\|\hat{\beta} - \beta_0\|^2 + \|\hat{\eta} - \eta_0\|_{L^2(Q)}^2 \right) = O_{\mathbb{P}}(1)$, where

$$\gamma_n = n^{\min(r\nu, \frac{1-\nu}{2})}$$

Hence, if $\nu = 1/(1+2r)$, the estimators converge at the optimal rate $n^{r/(1+2r)}$ and $\|\hat{\eta} - \eta_0\|_{\infty} \xrightarrow{P} 0$.

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$$\sqrt{n}(\hat{\beta} - \beta_0) \xrightarrow{D} N(0, \Sigma(\theta_0, \kappa_0)) .$$

Monte Carlo study

- $NR = 1000$ replications,
- samples of size $n = 100$,

The uncontaminated sample, C_0 , is generated as follows:

- (x_i, z_i) independent of each other, $x_i \sim N(0, 1)$, $z_i \sim \mathcal{U}(0, 1)$.
- $y_i = \beta_0 x_i + \eta_0(z_i) + u_i$,
 $u_i \sim \log(\Gamma(3, 1))$, $\beta_0 = 2$
- Two choices for the nonparametric component:

Model 1 $\eta_{0,1}(t) = \sin(\pi t/2)$

Model 2 $\eta_{0,2}(t) = \pi t + 0.25 \sin(4\pi t)$

Contaminations

We generate a sample $v_i \sim \mathcal{U}(0, 1)$ for $1 \leq i \leq n$ and then:

- C_1 introduces bad high leverage points in the carriers x , without changing the responses already generated:

$$y_{i,c} = y_i \quad x_{i,c} = \begin{cases} x_i & \text{if } v_i \leq 0.90 \\ x_i^* & \text{if } v_i > 0.90, \end{cases}$$

where $x_i^* \sim N(5, 1/16)$.

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- C_2 introduces outlying observations in the responses generated according to the model but with an incorrect carrier x .

$$y_{i,c} = \begin{cases} y_i & \text{if } v_i \leq 0.90 \\ y_i^* & \text{if } v_i > 0.90, \end{cases} \quad x_{i,c} = x_i$$

where $y_i^* = \beta_0 x_i^* + \eta_0(z_i) + u_i^*$ with

$$u_i^* \sim \log(\Gamma(3, 1)) \quad x_i^* \sim N(5, 1/16),$$

Contaminations

- C_3 corresponds to increasing the variance of the carriers x and also to introduce large values on the responses

$$x_{i,c} = \begin{cases} x_i & \text{if } v_i \leq 0.90 \\ \text{a new observation from a } N(0, 25) & \text{if } v_i > 0.90, \end{cases}$$
$$y_{i,c} = \begin{cases} y_i & \text{if } v_i \leq 0.90 \\ y_i^* & \text{if } v_i > 0.90, \end{cases}$$

with $y_i^* = 3 \log(10) + u_i^*$ and $u_i^* \sim \log(\Gamma(3, 1))$.

Results under C_0

Model 1							
Summary measures for $\hat{\beta}$							MISE($\hat{\eta}$)
Estimator	Bias	SD	MSE	AS.SE	Cov.Prob		
(a) CL	0.0002	0.0608	0.0037	0.0568	0.9340		0.0088
ROB	0.0021	0.0672	0.0045	0.0620	0.9270		0.0096

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a) Monotone B -splines

b) Isotone Modification

$$\text{ISE}(\hat{\eta}) = \frac{1}{n} \sum_{i=1}^n (\hat{\eta}(t_i) - \eta_0(t_i))^2 .$$

Results under C_0

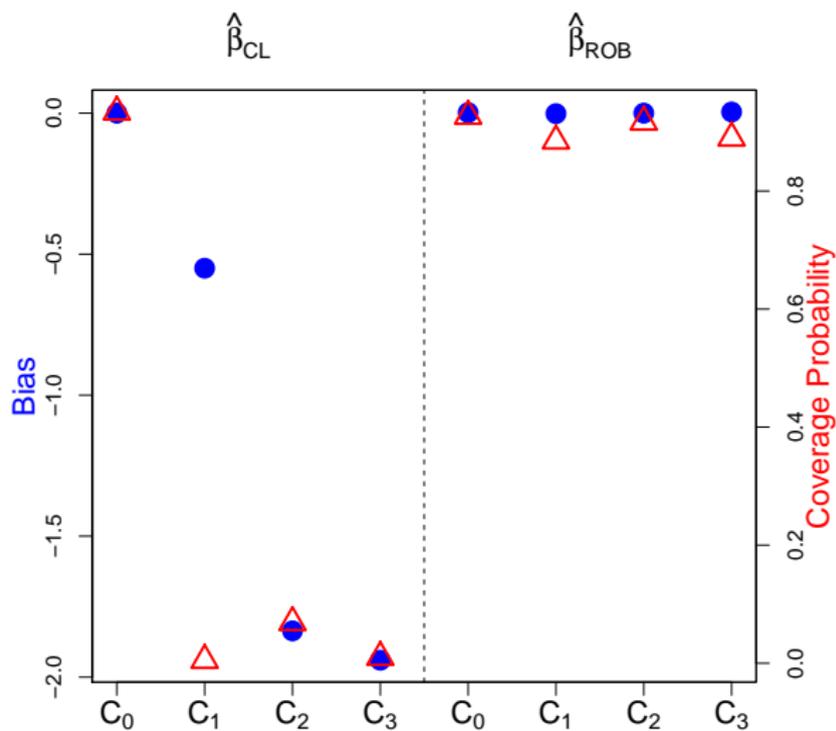
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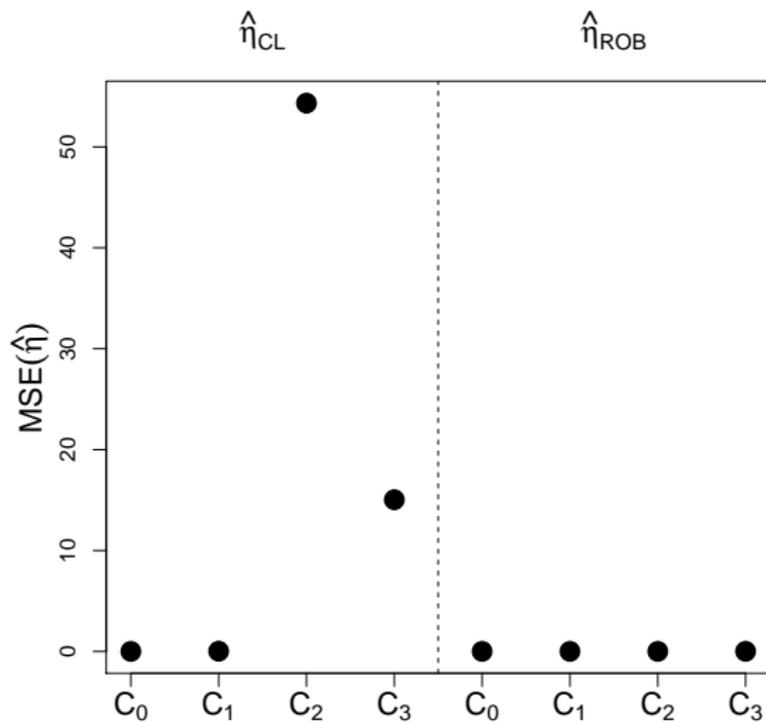
b) Isotone Modification

$$\text{ISE}(\hat{\eta}) = \frac{1}{n} \sum_{i=1}^n (\hat{\eta}(t_i) - \eta_0(t_i))^2 .$$

We will only present the results obtained when η_0 is estimated using Monotone B -splines

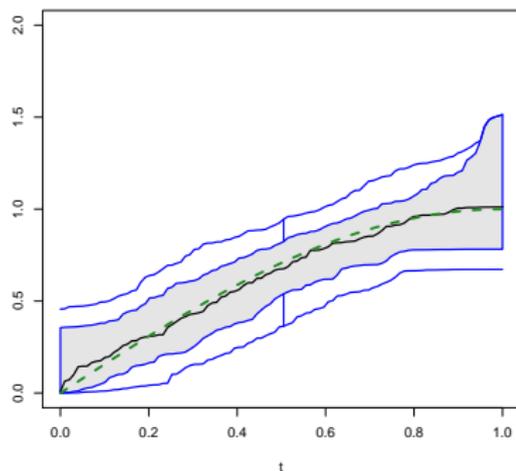
Performance of $\hat{\beta}$, Model 1

Performance of $\hat{\eta}$, Model 1

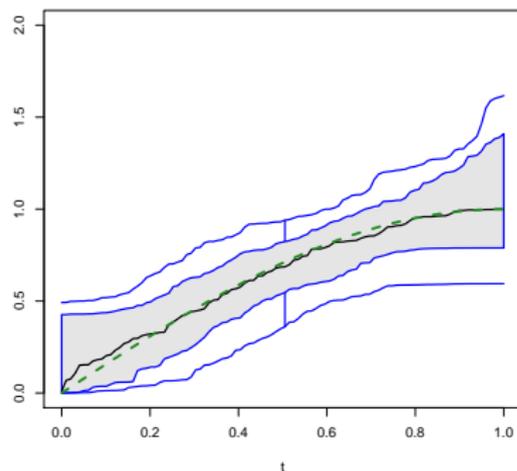


Performance of $\hat{\eta}$: C_0

CL

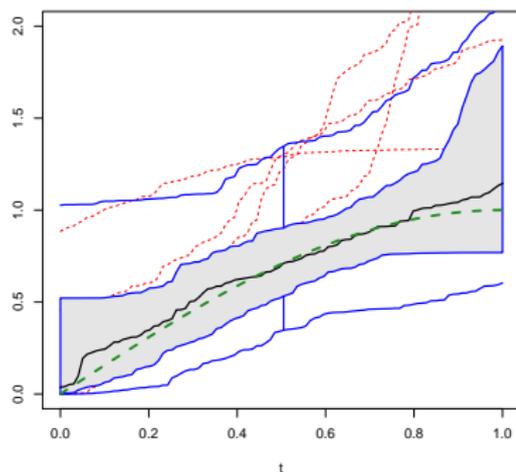


ROB

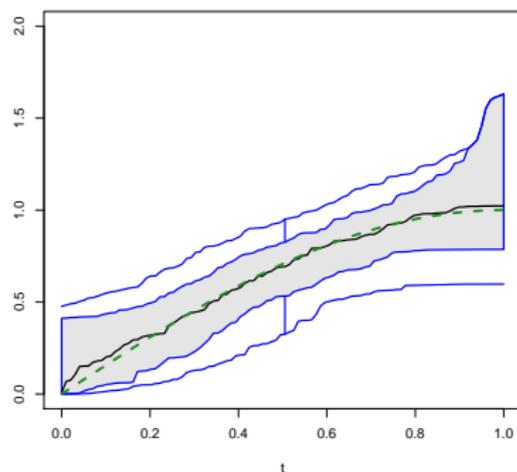


Performance of $\hat{\eta}$: C_1

CL

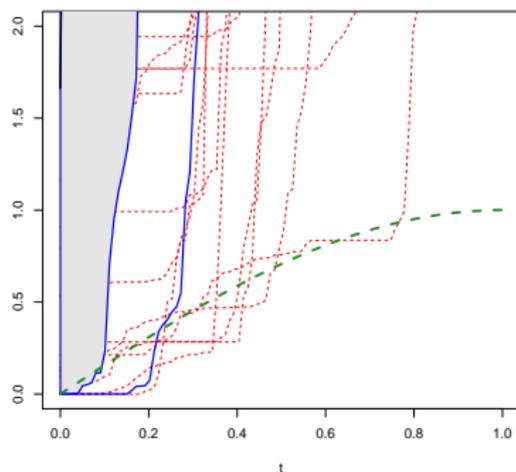


ROB

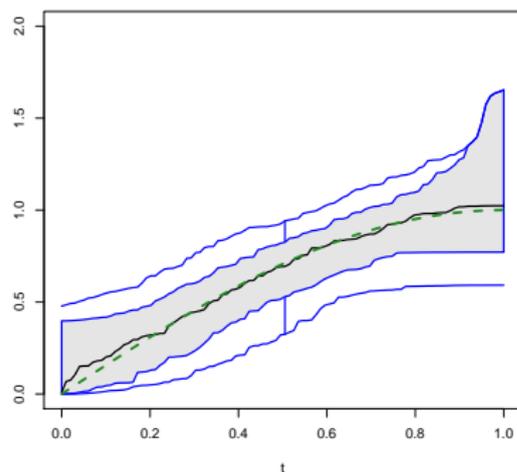


Performance of $\hat{\eta}$: C_2

CL

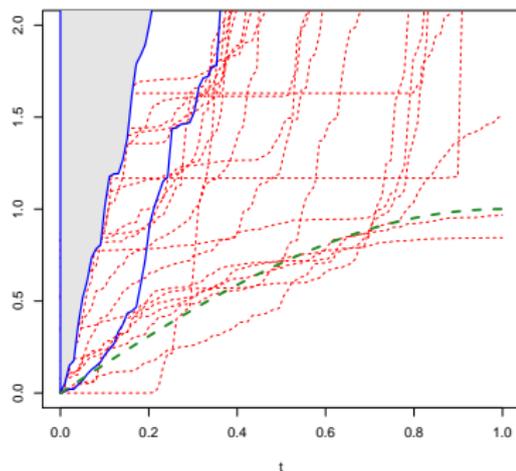


ROB

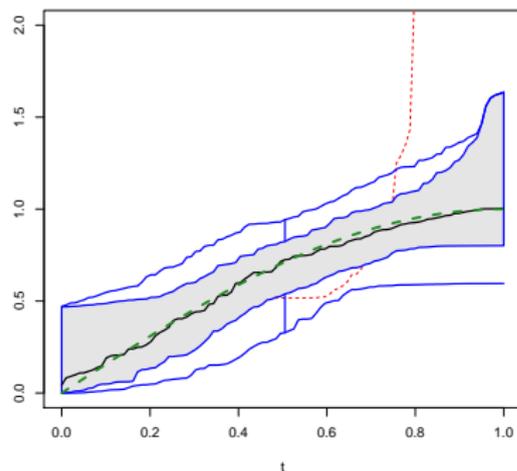


Performance of $\hat{\eta}$: C_3

CL

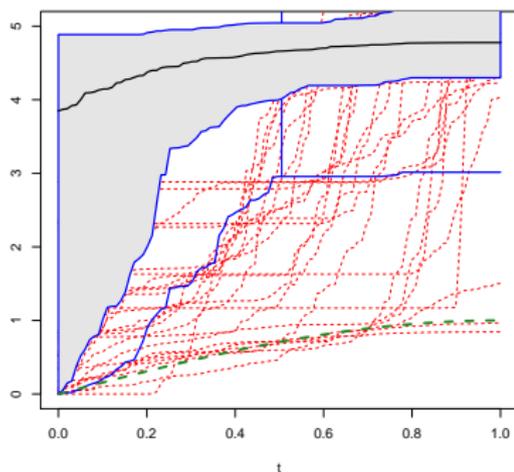


ROB

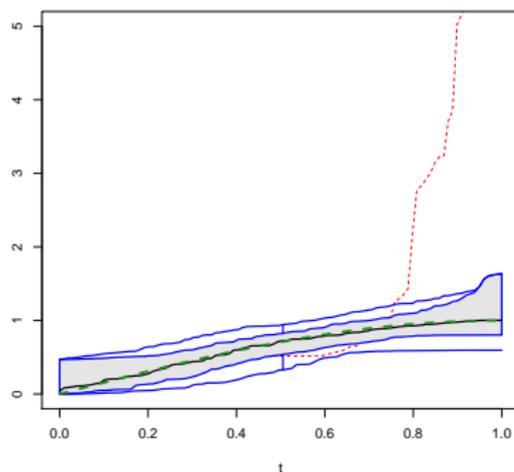


Performance of $\hat{\eta}$: C_3

CL



ROB



Hospital Costs Data (Marazzi and Yohai, 2004)

The data set corresponds to the costs of 100 patients hospitalized at the Centre Hospitalier Universitaire Vaudois in Lausanne (Switzerland) during 1999 for *medical back problems*.

Aim: Study the relationship between the **hospital cost of stay**, y , and the following **administrative explanatory variables**:

- LOS** length of stay in days
- ADM** admission type (0 = planned; 1 = emergency)
- INS** insurance type (0 = regular; 1 = private)
- AGE** years
- SEX** (0 = female; 1 = male)
- DEST** discharge destination (1 = home; 0 = another institution)

Linear fit approach

Cantoni and Ronchetti (2006) and Bianco *et al.* (2013) fitted a log-Gamma model to the data,

$$w_i | \mathbf{v}_i \sim \Gamma(\alpha, \mu_i) \quad \log(\mu_i) = \log(\mathbb{E}(z_i | \mathbf{v}_i)) = \boldsymbol{\gamma}_0^T \mathbf{v}_i$$

which is equivalent to a linear regression model with asymmetric errors

$$y_i = \log(w_i) = \boldsymbol{\gamma}_0^T \mathbf{v}_i + u_i,$$

- $u_i \sim \log \Gamma(\alpha, 1)$
- $\mathbf{v} = (ADM, INS, AGE, SEX, DEST, \log(LOS), 1)$

Using a robust QL approach Cantoni and Ronchetti (2006) identified 5 outliers ($i = 14, 21, 28, 44$ and 63), affecting the classical estimates of *INS* and the shape parameter.

Our setting

We will not impose a linear relation between $\log(y_i)$ and the $\log(LOS)$.

$$y_i = \beta_0^T \mathbf{x}_i + \eta_0(z_i) + u_i$$

- $u_i \sim \log \Gamma(\alpha, 1)$,
- $\mathbf{x} = (ADM, INS, AGE, SEX, DEST)$, $z = \log(LOS)$.
- $\eta_0 : \mathbb{R} \rightarrow \mathbb{R}$ is an increasing function.
- *BIC* criterion:
 - ▶ $\hat{\beta}_{CL}$ $k_n = 4$
 - ▶ $\hat{\beta}_R$ $k_n = 5$ $c_\rho = 0.3515$

Hospital Costs Data

	<i>ADM</i>	<i>INS</i>	<i>AGE</i>	<i>SEX</i>	<i>DEST</i>	$\hat{\alpha}$
$\hat{\beta}_{CL}$	0.2148 (0.0497)	0.0984 (0.0792)	-0.0009 (0.0013)	0.1088 (0.0529)	-0.1358 (0.0723)	21.0809
$\hat{\beta}_R$	0.1979 (0.0339)	-0.0207 (0.0537)	-0.0019 (0.0009)	0.0615 (0.0358)	-0.1673 (0.0493)	46.0088

Hospital Costs Data

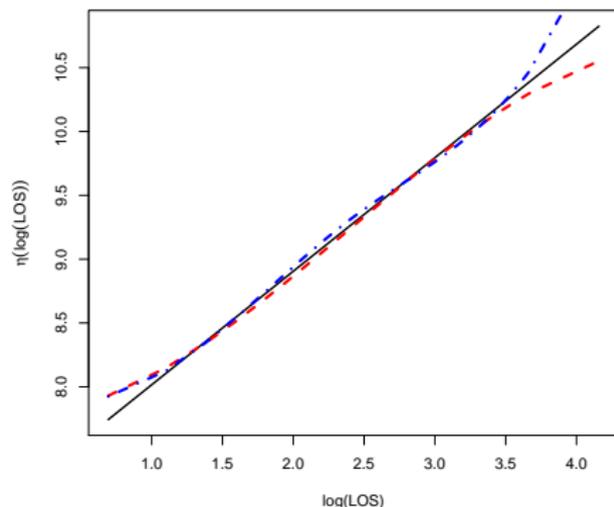
	<i>ADM</i>	<i>INS</i>	<i>AGE</i>	<i>SEX</i>	<i>DEST</i>	$\hat{\alpha}$
$\hat{\beta}_{CL}$	0.2148 (0.0497)	0.0984 (0.0792)	-0.0009 (0.0013)	0.1088 (0.0529)	-0.1358 (0.0723)	21.0809
$\hat{\beta}_R$	0.1979 (0.0339)	-0.0207 (0.0537)	-0.0019 (0.0009)	0.0615 (0.0358)	-0.1673 (0.0493)	46.0088
$\hat{\beta}_{CL}^{-\{5\}}$	0.2172 (0.0345)	-0.0324 (0.0575)	-0.0016 (0.0009)	0.0820 (0.0354)	-0.1608 (0.0489)	45.7560

Analysis of Hospital Costs data, between brackets are reported the estimated asymptotic standard deviations of the estimators.

- As in the linear fit, the classical estimator of β are highly affected by the 5 outliers, which were also detected in our study.
- After removing these 5 data points, the classical estimators $\hat{\beta}_{CL}^{-\{5\}}$ are very similar to those obtained using $\hat{\beta}_R$, showing its good performance in presence of outliers.

Hospital Costs Data

$$\hat{\eta}(z) = 0.8892z + 7.1268$$



$\hat{\eta}_{CL}$ in red

$\hat{\eta}_R$ in blue

- The linear fit (in black) seems to be a good choice for this data set, however, some discrepancies appear near the boundary.
- It is worth noting that in this case, the shape of the classical estimator (in red) is quite close to that of the robust one (in blue).

Summary

- We have defined a robust estimators for the regression parameter and the nonparametric function under the constraint that η_0 monotone.
- Our estimators are consistent and attain the optimal convergence rate.
- The estimators of the regression coefficient are asymptotically normally distributed.
- The simulation study illustrate the bad behaviour of the classical estimator when outliers are present.
- In particular, expected large responses affect the classical estimators of the nonparametric component.

Thanks for your attention.

Algorithm

Denote $\psi = \rho'$ and

$$r_i(\mathbf{b}, \mathbf{a}) = y_i - \mathbf{x}_i^T \mathbf{b} - \sum_{j=1}^{k_n} a_j B_j(z_i)$$

- **Step 1:**

Let $m = 0$ and $(\mathbf{b}^{(0)}, \mathbf{a}^{(0)}) = (\hat{\boldsymbol{\beta}}, \hat{\mathbf{a}})$ the *MM*-estimators computed without restrictions and $\hat{\sigma}$ the scale given in the S-step.

- **Step 2:**

- ▶ Given m define the weights

$$w_{i,m} = \psi \left(\frac{r_i(\mathbf{b}^{(m)}, \mathbf{a}^{(m)})}{\hat{\sigma}} \right) \frac{\hat{\sigma}}{r_i(\mathbf{b}^{(m)}, \mathbf{a}^{(m)})}$$

- ▶ Define

$$y_{w,i} = w_{i,m}^{1/2} y_i \quad , \quad x_{w,il} = w_{i,m}^{1/2} x_{il} \quad , \quad B_{w,il} = w_{i,m}^{1/2} B_l(z_i)$$

Algorithm

• Step 2:

- ▶ Define

$$y_{w,i} = w_{i,m}^{1/2} y_i \quad , \quad x_{w,il} = w_{i,m}^{1/2} x_{il} \quad , \quad B_{w,il} = w_{i,m}^{1/2} B_\ell(z_i)$$

- ▶ Let $\mathbf{v}_i = (x_{w,i1}, \dots, x_{w,ip_1}, B_{w,i1}, \dots, B_{w,ip_2})^\top$, $\mathbf{y}_w = (y_{w,1}, \dots, y_{w,n})^\top$ and $\mathbf{d} = (\boldsymbol{\beta}^\top, \boldsymbol{\lambda}^\top)^\top$. We solve the quadratic problem with monotone restrictions

$$\hat{\mathbf{d}} = \min_{\mathbf{b}, a_1 \leq \dots \leq a_{k_n}} \|\mathbf{y}_w - \mathbf{V}^\top \mathbf{d}\|^2 = \min_{\mathbf{b}, a_1 \leq \dots \leq a_{k_n}} \sum_{i=1}^n w_{i,m} r_i^2(\mathbf{b}, \mathbf{a})$$

- ▶ Define $\mathbf{b}^{(m+1)}$ as the first p components of $\hat{\mathbf{d}}$ and $\mathbf{a}^{(m+1)}$ as the last ones.
- Go to step 2 and iterate until convergence.

Algorithm

- **Step 1.**

Step 1.1 Compute an initial S -estimator $\tilde{\nu} = (\tilde{\beta}_n, \tilde{\mathbf{a}}_n)$ as in Bianco *et al.* (2005), i.e.,

$$\tilde{\nu}_n = \underset{\mathbf{b}, \mathbf{a}}{\operatorname{argmin}} \sigma_n(\mathbf{b}, \mathbf{a})$$

where

$$\frac{1}{n} \sum_{i=1}^n \rho \left(\frac{\sqrt{d(y_i - \mathbf{b}^T \mathbf{x}_i - \mathbf{a}^T \mathbf{B}_i)}}{\sigma_n(\mathbf{b}, \mathbf{a})} \right) = \frac{1}{2},$$

$$\hat{\sigma}_n = \sigma_n(\tilde{\beta}_n, \tilde{\mathbf{a}}_n)$$

Algorithm

- **Step 1.2.**

Let $u \sim \log \Gamma(\alpha, 1)$ and $\sigma^*(\alpha)$ the solution of

$$\mathbb{E} \left[\rho \left(\frac{\sqrt{1 - u - \exp(u)}}{\sigma^*(\alpha)} \right) \right] = \frac{1}{2},$$

Compute

$$\blacktriangleright \hat{\alpha}_n = \sigma^{*-1}(\hat{\sigma}_n) \qquad \blacktriangleright \hat{\kappa}_n = \max(\hat{\sigma}_n, C_e(\hat{\alpha}_n)).$$

- Let $\hat{\nu}_n^{(0)}$ be *WMM*-estimator of ν defined as

$$\hat{\nu}_n^{(0)} = \underset{(\mathbf{b}, \mathbf{a})}{\operatorname{argmin}} \sum_{i=1}^n \rho \left(\frac{\sqrt{d(y_i - \mathbf{b}^T \mathbf{x}_i - \mathbf{a}^T \mathbf{B}_i)}}{\hat{\kappa}_n} \right) w(\mathbf{x}_i).$$

Algorithm

- **Step 2.**

- ★ If $\hat{a}_1^{(0)} \leq \hat{a}_2^{(0)} \leq \dots \leq \hat{a}_{k_n}^{(0)}$, the final estimators are $\hat{\beta} = \hat{\beta}^{(0)}$ and $\hat{\eta}(t) = \sum_{j=1}^{k_n} \hat{a}_j^{(0)} B_j(t)$.

- ★ Otherwise, the final estimators are obtained using a standard minimization algorithm with restrictions choosing as initial value $(\hat{\beta}_n^{(0)}, \mathbf{a}^0)$, where $\mathbf{a}^0 \in \mathcal{L}_{k_n}$.

One possible choice for \mathbf{a}^0 is $a_1^0 = a_2^0 = 0$ and $a_i^0 = i - 2$ for $i = 3, \dots, k_n$.

Algorithm: Generalised Rosen Algorithm (Jamshidian, 2004)

- Denote $\widehat{\nabla}$ the gradient function and $\widehat{\mathbf{H}}$ the gradient and negative Hessian of the objective function. Let $\mathcal{A} = \{i_1, \dots, i_m\}$ the set of indices such that $a_{i_j}^{(0)} = a_{i_j+1}^{(0)}$. If $m > 0$ define the working matrix as $\mathbf{A} \in \mathbb{R}^{m \times (k_n + \rho)}$ in which the j -th row is the vector with its i_j -th element equal to 1 and the $(i_j + 1)$ -th element equal to -1 , the remaining ones equal to 0.
- Fix an initial value $\boldsymbol{\nu}$ (in the first step, $\boldsymbol{\nu} = (\widehat{\beta}_n^{(0)}, \mathbf{a}^0)$) and denote $\widehat{\mathbf{H}} = \widehat{\mathbf{H}}(\boldsymbol{\nu})$, $\widehat{\nabla} = \widehat{\nabla}(\boldsymbol{\nu})$.
- S1** Find the feasible direction as

$$\boldsymbol{\eta} = \left(\mathbf{I} - \widehat{\mathbf{H}}^{-1} \mathbf{A}^T \left(\mathbf{A} \widehat{\mathbf{H}}^{-1} \mathbf{A}^T \right)^{-1} \mathbf{A} \right) \widehat{\mathbf{H}}^{-1} \widehat{\nabla}$$

Algorithm

- **S2** If $\|\boldsymbol{\eta}\| < \epsilon$ for some $\epsilon > 0$ small enough, compute the Lagrange multipliers

$$\boldsymbol{\mu} = \left(\mathbf{A}\hat{\mathbf{H}}^{-1}\mathbf{A}^T \right)^{-1} \mathbf{A}\hat{\mathbf{H}}^{-1}\hat{\boldsymbol{\nu}}$$

Let μ_i be the i -th component of $\boldsymbol{\mu}$.

- ▶ If $\mu_i \geq 0$, for all $i \in \mathcal{A}$, then $\hat{\boldsymbol{\nu}} = \boldsymbol{\nu}$.
 - ▶ If there exists at least one $i \in \mathcal{A}$ such that $\mu_i < 0$, determine the index corresponding to the largest μ_i and remove it from \mathcal{A} and go to **S1**.
- **S3** Compute

$$\theta_1 = \min_{\eta_i > \eta_{i+1}, i \notin \mathcal{A}, 1 \leq i \leq k_n - 1} \frac{-(a_{i+1} - a_i)}{\eta_{i+1} - \eta_i}$$

and find the smallest r such that $L_n(\boldsymbol{\nu} + 2^{-r}\boldsymbol{\eta}) > L_n(\boldsymbol{\nu})$. Then replace $\boldsymbol{\nu}$ by $\tilde{\boldsymbol{\nu}} = \boldsymbol{\nu} + \min(2^{-r}, \theta_1)\boldsymbol{\eta}$, update \mathcal{A} and \mathbf{A} and go to **S1**.

Results when $\eta_0 = \eta_{0,1}$

		Summary measures for $\hat{\beta}$			MISE($\hat{\eta}$)
Estimator		Bias	MSE	Cov.Prob	
C_0	CL	0.0002	0.0037	0.9340	0.0088
	ROB	0.0021	0.0045	0.9270	0.0096

Results when $\eta_0 = \eta_{0,1}$

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	ROB	0.0021	0.0045	0.9270	0.0096
C_1	CL	-0.5497	0.3492	0.0050	0.0265
	ROB	-0.0016	0.0050	0.8850	0.0100

Results when $\eta_0 = \eta_{0,1}$

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Estimator		Bias	MSE	Cov.Prob	
C_0	CL	0.0002	0.0037	0.9340	0.0088
	ROB	0.0021	0.0045	0.9270	0.0096
C_2	CL	-1.8359	4.2426	0.0690	54.3390
	ROB	0.0002	0.0051	0.9170	0.0103

Results when $\eta_0 = \eta_{0,1}$

		Summary measures for $\hat{\beta}$			MISE($\hat{\eta}$)
Estimator		Bias	MSE	Cov.Prob	
C_0	CL	0.0002	0.0037	0.9340	0.0088
	ROB	0.0021	0.0045	0.9270	0.0096

C_3	CL	-1.9400	3.8376	0.0100	15.0401
	ROB	0.0043	0.0053	0.8900	0.0146

Results

Model 1							
Summary measures for $\hat{\beta}$							MISE($\hat{\eta}$)
Estimator		Bias	SD	MSE	AS.SE	Cov.Prob	
C_0	CL	0.0002	0.0608	0.0037	0.0568	0.9340	0.0088
	ROB	0.0021	0.0672	0.0045	0.0620	0.9270	0.0096

Results

Model 1							
Summary measures for $\hat{\beta}$							MISE($\hat{\eta}$)
Estimator		Bias	SD	MSE	AS.SE	Cov.Prob	
C_0	CL	0.0002	0.0608	0.0037	0.0568	0.9340	0.0088
	ROB	0.0021	0.0672	0.0045	0.0620	0.9270	0.0096
C_1	CL	-0.5497	0.2170	0.3492	0.0535	0.0050	0.0265
	ROB	-0.0016	0.0706	0.0050	0.0591	0.8850	0.0100

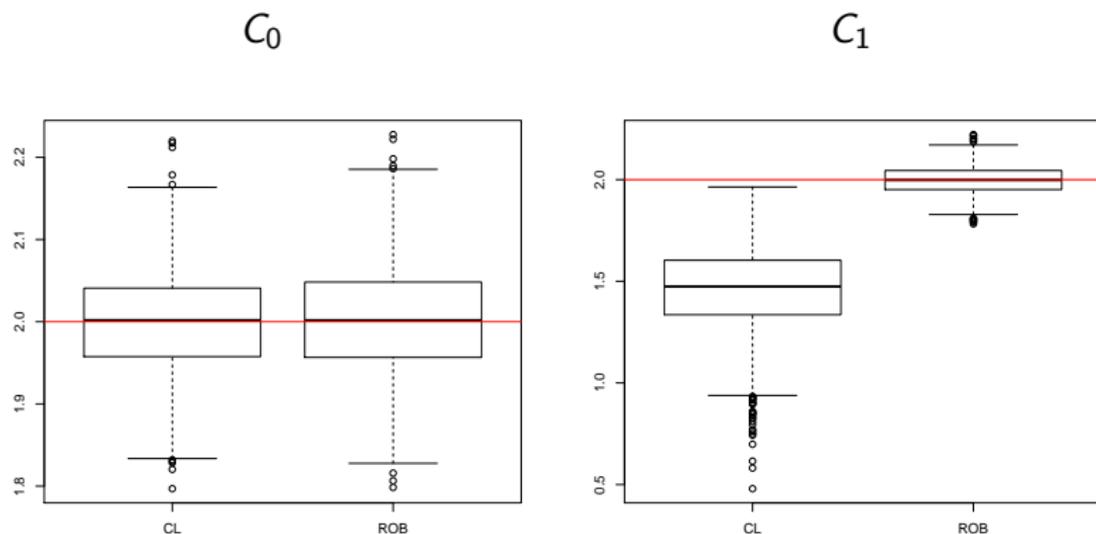
Results

Model 1							
Summary measures for $\hat{\beta}$							MISE($\hat{\eta}$)
Estimator		Bias	SD	MSE	AS.SE	Cov.Prob	
C_0	CL	0.0002	0.0608	0.0037	0.0568	0.9340	0.0088
	ROB	0.0021	0.0672	0.0045	0.0620	0.9270	0.0096
C_2	CL	-1.8359	0.9343	4.2426	0.3781	0.0690	54.3390
	ROB	0.0002	0.0711	0.0051	0.0639	0.9170	0.0103

Results

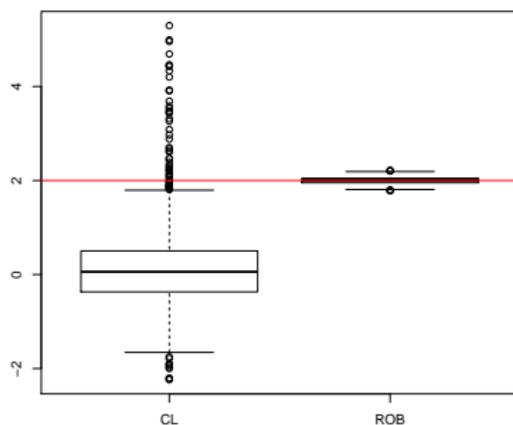
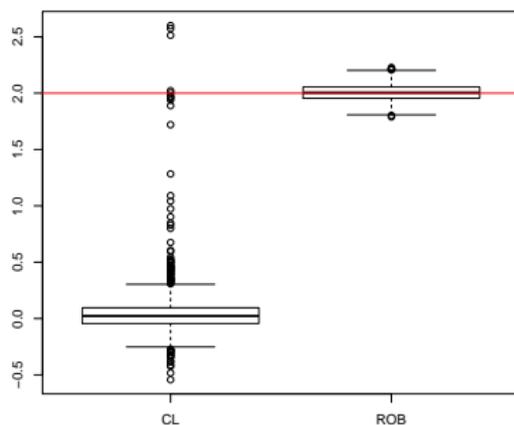
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	ROB	0.0021	0.0672	0.0045	0.0620	0.9270	0.0096
C_3	CL	-1.9400	0.2721	3.8376	0.1848	0.0100	15.0401
	ROB	0.0043	0.0727	0.0053	0.0598	0.8900	0.0146

Boxplots for $\hat{\beta}$, Model 1



Boxplots of $\hat{\beta}$, under a Gamma Model with $\eta_0 = \eta_{0,1}$, $c_w = \sqrt{\chi_{0.975,1}^2}$.

Boxplots for $\hat{\beta}$, Model 1

 C_2

 C_3


Boxplots of $\hat{\beta}$, under a Gamma Model with $\eta_0 = \eta_{0,1}$, $c_w = \sqrt{\chi_{0.975,1}^2}$.